

Solutions to HW 3

5.4

$$(8a.) \theta = \cos^{-1} \left(\frac{\langle 1, x \rangle}{\|1\| \cdot \|x\|} \right) \Rightarrow \langle 1, x \rangle = \int_0^1 x \, dx = x/2 \Big|_0^1 = 1/2$$

$$\|1\| = \sqrt{\int_0^1 1 \, dx} = 1$$

$$\|x\| = \sqrt{\int_0^1 x^2 \, dx} = \sqrt{\frac{x^3}{3} \Big|_0^1} = \sqrt{1/3}$$

$$\Rightarrow \boxed{\theta = 1.2780}$$

$$(8b.) \boxed{\bar{p} = \frac{\langle 1, x \rangle}{\langle x, x \rangle} x = \frac{1/2}{1/3} x = \frac{3}{2} x}$$

$$\langle 1 - \frac{3}{2}x, \frac{3}{2}x \rangle = \int_0^1 \frac{3}{2}x - \frac{9}{4}x^2 \, dx = \frac{3}{2} \frac{x^2}{2} \Big|_0^1 - \frac{9}{4} \frac{x^3}{3} \Big|_0^1 = 0$$

$\Rightarrow 1 - \bar{p}$ and \bar{p} are orthogonal.

$$(8c.) \|\bar{p}\|^2 = \int_0^1 \left(\frac{3}{2}x\right)^2 \, dx = \int_0^1 \frac{9}{4}x^2 \, dx = \frac{3}{4}$$

$$\|1\|^2 = 1$$

$$\|1 - \bar{p}\|^2 = \int_0^1 1 - 3x + \frac{9}{4}x^2 \, dx = \left[x - \frac{3}{2}x^2 + \frac{3x^3}{4} \right]_0^1 = \sqrt{\frac{1}{4}}$$

$$\|1\|^2 = 1$$

$$\|1 - p\|^2 = \frac{1}{4}$$

$$\|\bar{p}\|^2 = \frac{3}{4}$$

$$\Rightarrow \|1\|^2 = \|1 - p\|^2 + \|\bar{p}\|^2$$

5.5

$$(6.) \langle \bar{u}, \bar{v} \rangle = \langle \bar{u}_1 + 2\bar{u}_2 + 2\bar{u}_3, \bar{u}_1 + 7u_3 \rangle = \langle \bar{u}_1, \bar{u}_1 \rangle + \langle 2u_3, 7u_3 \rangle$$

$$= 1 + 14 = \boxed{15}$$

$$\|\bar{u}\| = \sqrt{\langle \bar{u}, \bar{u} \rangle} = \sqrt{\langle \bar{u}_1, \bar{u}_1 \rangle + \langle 2\bar{u}_2, 2\bar{u}_2 \rangle + \langle 2\bar{u}_3, 2\bar{u}_3 \rangle} = \sqrt{1+4+4} = \boxed{3}$$

$$\|\bar{v}\| = \sqrt{\langle \bar{v}, \bar{v} \rangle} = \sqrt{\langle \bar{u}_1, \bar{u}_1 \rangle + \langle 7u_3, 7u_3 \rangle} = \sqrt{50}$$

$$\Rightarrow \theta = \cos^{-1} \left(\frac{15}{3 \cdot \sqrt{50}} \right) = \cos^{-1} \left(\frac{1}{\sqrt{2}} \right) = \boxed{\frac{\pi}{4}}$$

$$(9a.) \sin^4 x = \frac{1}{2} \frac{1 - \cos 2x}{2} = \frac{3}{8} - \frac{\cos 2x}{2} + \frac{\cos 4x}{8} = \frac{3\sqrt{2}}{8} \cdot \frac{1}{\sqrt{2}} - \frac{1}{2} \cos 2x + \frac{1}{8} \cos 4x$$

$$(b.i.) \int_{-\pi}^{\pi} \sin^4 x \cos x \, dx = \frac{3}{8} \pi \langle \sin^4 x, \cos x \rangle = \pi \cdot 0 = \boxed{0}$$

$$(b.ii.) \int_{-\pi}^{\pi} \sin^4 x \cos 2x \, dx = \pi \langle \sin^4 x, \cos 2x \rangle = \pi \left(-\frac{1}{2} \right) = \boxed{-\frac{\pi}{2}}$$

$$(b.iii.) \int_{-\pi}^{\pi} \sin^4 x \cos 3x \, dx = \pi \langle \sin^4 x, \cos 3x \rangle = \pi \cdot 0 = \boxed{0}$$

$$(b.iv.) \int_{-\pi}^{\pi} \sin^4 x \cos 4x \, dx = \pi \langle \sin^4 x, \cos 4x \rangle = \pi \cdot \left(\frac{1}{8} \right) = \boxed{\frac{\pi}{8}}$$

5.5

(27a) $\langle 1, x \rangle = \int_{-1}^1 x \, dx = \frac{x^2}{2} \Big|_{-1}^1 = 0 \Rightarrow$ they are orthogonal

(27b.) $\|1\| = \sqrt{\langle 1, 1 \rangle} = \sqrt{\int_{-1}^1 1 \, dx} = \sqrt{x \Big|_{-1}^1} = \sqrt{2}$

$\|x\| = \sqrt{\langle x, x \rangle} = \sqrt{\int_{-1}^1 x^2 \, dx} = \sqrt{\frac{x^3}{3} \Big|_{-1}^1} = \sqrt{2/3}$

(27c.) $\bar{p} = \bar{p}_1 + \bar{p}_2$ where $\bar{p}_1 = \frac{\langle x^{1/3}, 1 \rangle}{\langle 1, 1 \rangle} 1$ and $\bar{p}_2 = \frac{\langle x^{1/3}, x \rangle}{\langle x, x \rangle} x$

$\Rightarrow \bar{p}_1 = \frac{\langle x^{1/3}, 1 \rangle}{\langle 1, 1 \rangle} = \frac{\int_{-1}^1 x^{1/3} \, dx}{\int_{-1}^1 1 \, dx} = \frac{x^{4/3} \Big|_{-1}^1}{4/3} = 0 \Rightarrow \bar{p}_1 = 0$

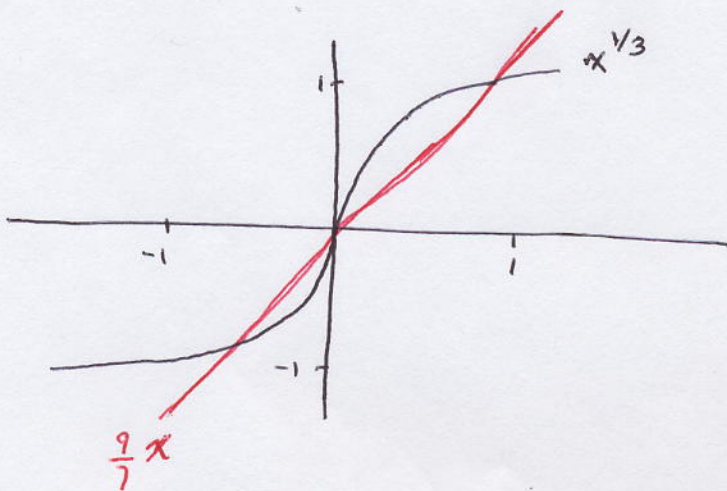
$\langle x^{1/3}, x \rangle = \int_{-1}^1 x^{4/3} \, dx = 2 \int_0^1 x^{4/3} \, dx = 2 \cdot \frac{x^{7/3}}{7/3} \Big|_0^1 = \frac{6}{7}$

$\Rightarrow \bar{p}_2 = \frac{6/7}{2/3} x = \frac{9}{7} x$

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$\Rightarrow \bar{p} = \frac{9}{7} x$

(27d.)



5.6

$$(8.) \bar{y}_1 = \bar{x}_1 = \begin{pmatrix} 4 \\ 2 \\ 1 \end{pmatrix} \Rightarrow \boxed{\bar{z}_1 = \begin{pmatrix} 0.8 \\ 0.4 \\ 0.4 \\ 0.2 \end{pmatrix}}$$

$$\bar{y}_2 = \bar{x}_2 - \frac{\langle \bar{x}_2, \bar{y}_1 \rangle}{\langle \bar{y}_1, \bar{y}_1 \rangle} \bar{y}_1 = \begin{pmatrix} 0.4 \\ -0.8 \\ -0.8 \\ 1.6 \end{pmatrix} \Rightarrow \boxed{\bar{z}_2 = \begin{pmatrix} 0.2 \\ -0.4 \\ -0.4 \\ 0.8 \end{pmatrix}}$$

$$\bar{y}_3 = \bar{x}_3 - \frac{\langle \bar{x}_3, \bar{y}_1 \rangle}{\langle \bar{y}_1, \bar{y}_1 \rangle} \bar{y}_1 - \frac{\langle \bar{x}_3, \bar{y}_2 \rangle}{\langle \bar{y}_2, \bar{y}_2 \rangle} \bar{y}_2 = \begin{pmatrix} 0 \\ -1 \\ 0 \end{pmatrix}$$

$$\Rightarrow \boxed{\bar{z}_3 = \begin{pmatrix} 0 \\ 0.7071 \\ -0.7071 \\ 0 \end{pmatrix}}$$