

EXAM 1 Solutions (Review)

(1a.) Yes: $L(\bar{x} + \bar{y}) = (x_3 + y_3 + x_2 + y_2, x_1 + y_1 + x_2 + y_2)^T = (x_3 + x_2 + y_3 + y_2, x_1 + x_2 + y_1 + y_2)^T$
 $L(\bar{x}) + L(\bar{y}) = (x_3 + x_2, x_1 + x_2)^T + (y_3 + y_2, y_1 + y_2)^T = L(\bar{x} + \bar{y})$
 $L(\alpha \bar{x}) = (\alpha x_3 + \alpha x_2, \alpha x_1 + \alpha x_2)^T = \alpha (x_3 + x_2, x_1 + x_2)^T = \alpha L(\bar{x})$

(1b.) No: $L(\bar{0}) = (0, 1)^T \neq (0, 0)$

(1c.) Yes

$$L(f(x) + g(x)) = (f+g)'(0)x + (f+g)(0) = f'(0)x + f(0) + g'(0)x + g(0) = L(f(x)) + L(g(x))$$

$$L(\alpha f(x)) = (\alpha f)'(0)x + (\alpha f)(0) = \alpha [f'(0)x + f(0)] = \alpha L(f(x))$$

(2.) $\ker(L) = \left\{ \begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix} \mid x_1 - x_2 = 0, x_2 - x_3 = 0, x_3 - x_1 = 0 \right\}$
 $= \left\{ \begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix} \mid x_1 = x_2 = x_3 \right\} = \text{Span} \left(\begin{pmatrix} 1 \\ 1 \\ 1 \end{pmatrix} \right) \Rightarrow$ basis for $\ker(L)$ is $\left\{ \begin{pmatrix} 1 \\ 1 \\ 1 \end{pmatrix} \right\}$

$$L(\mathbb{R}^3) = \text{Span} \left(L \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix}, L \begin{pmatrix} 0 \\ 1 \\ 0 \end{pmatrix}, L \begin{pmatrix} 0 \\ 0 \\ 1 \end{pmatrix} \right) = \text{Span} \left(\begin{pmatrix} 1 \\ 0 \\ -1 \end{pmatrix}, \begin{pmatrix} -1 \\ 1 \\ 0 \end{pmatrix}, \begin{pmatrix} 0 \\ -1 \\ 1 \end{pmatrix} \right)$$

$$= \text{Col}(A) \text{ where } A = \begin{pmatrix} 1 & -1 & 0 \\ 0 & 1 & -1 \\ -1 & 0 & 1 \end{pmatrix} \xrightarrow{\text{rref}} \begin{pmatrix} 1 & 0 & -1 \\ 0 & 1 & -1 \\ 0 & 0 & 0 \end{pmatrix} \Rightarrow$$
 a basis for $L(\mathbb{R}^3)$ is

is $\left\{ \begin{pmatrix} 1 \\ 0 \\ -1 \end{pmatrix}, \begin{pmatrix} -1 \\ 1 \\ 0 \end{pmatrix} \right\}$

Note: A is just the matrix rep. of L wrt the standard basis for \mathbb{R}^3

$$(3a.) \quad L\left(\begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix}\right) = \begin{pmatrix} 2 \\ 0 \end{pmatrix} \quad L\left(\begin{pmatrix} 0 \\ 1 \\ 0 \end{pmatrix}\right) = \begin{pmatrix} -1 \\ 1 \end{pmatrix} \quad L\left(\begin{pmatrix} 0 \\ 0 \\ 1 \end{pmatrix}\right) = \begin{pmatrix} 0 \\ -4 \end{pmatrix}$$

$$\Rightarrow \text{the matrix rep. of } L \text{ is } \boxed{A = \begin{pmatrix} 2 & -1 & 0 \\ 0 & 1 & -4 \end{pmatrix}}$$

$$(3b.) \quad L(x^2) = 2x + 1 \quad L(x) = 0 \quad L(1) = 1 \\ = \begin{pmatrix} 2 \\ 1 \end{pmatrix} \quad = \begin{pmatrix} 0 \\ 0 \end{pmatrix} \quad = \begin{pmatrix} 0 \\ 1 \end{pmatrix}$$

$$\Rightarrow \text{matrix rep. of } L \text{ is } \boxed{A = \begin{pmatrix} 2 & 0 & 0 \\ 1 & 0 & 1 \end{pmatrix}}$$

$$(4.) \quad L(\bar{u}_1) = \begin{pmatrix} 22 \\ -13 \end{pmatrix} \quad L(\bar{u}_2) = \begin{pmatrix} 14 \\ -4 \end{pmatrix} \quad L(\bar{u}_3) = \begin{pmatrix} -23 \\ 17 \end{pmatrix}$$

$$\Rightarrow \text{the matrix wrt to } [\bar{u}_1, \bar{u}_2, \bar{u}_3] \text{ and } [\bar{e}_1, \bar{e}_2] \text{ is } A = \begin{pmatrix} 22 & 14 & -23 \\ -13 & -4 & 17 \end{pmatrix}$$

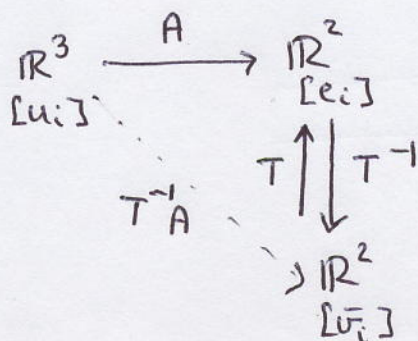
Now the transition matrix from $[\bar{v}_1, \bar{v}_2]$ to $[\bar{e}_1, \bar{e}_2]$ is

$$T = \begin{pmatrix} 2 & -2 \\ -2 & 1 \end{pmatrix} \Rightarrow \text{the transition from } [\bar{e}_1, \bar{e}_2] \text{ to } [\bar{v}_1, \bar{v}_2] \text{ is}$$

$$T^{-1} = \begin{pmatrix} -1/2 & -1 \\ -1 & -1 \end{pmatrix}$$

Therefore the matrix rep. of L wrt $[\bar{u}_1, \bar{u}_2, \bar{u}_3]$ and $[\bar{v}_1, \bar{v}_2]$

$$\text{is } \boxed{T^{-1}A = \begin{pmatrix} 2 & -3 & -11/2 \\ -9 & -10 & 6 \end{pmatrix}}$$



(5.) The transition matrix from $[3x^2+2x+11, x^2+1, -9x^2-8x+7]$

to $[x^2, x, 1]$ is

$$T = \begin{pmatrix} 3 & 1 & -9 \\ 2 & 0 & -8 \\ 11 & 1 & 7 \end{pmatrix}$$

\Rightarrow the matrix rep of L wrt $[3x^2+2x+11, x^2+1, -9x^2-8x+7]$

is given by

$$B = T^{-1}AT = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 3 & 0 \\ 0 & 0 & -5 \end{pmatrix}$$

(6a) $\langle 1, x \rangle = \int_{-1}^1 x dx = \frac{x^2}{2} \Big|_{-1}^1 = 0$

$\langle 1, 3x^2-1 \rangle = \int_{-1}^1 3x^2-1 dx = x^3 - x \Big|_{-1}^1 = 0$

$\langle x, 3x^2-1 \rangle = \int_{-1}^1 3x^3-x dx = \frac{3x^4}{4} - \frac{x^2}{2} \Big|_{-1}^1 = 0$

} It is an orthogonal basis

(6b.) $\bar{p} = \bar{p}_1 + \bar{p}_2 + \bar{p}_3$

$$\bar{p}_1 = \frac{\langle 1, x^{4/3} \rangle}{\langle 1, 1 \rangle} = \frac{\int_{-1}^1 x^{4/3} dx}{\int_{-1}^1 1 dx} \cdot 1 = \frac{6/7}{2} \cdot 1 = \frac{3}{7} \cdot 1$$

$$\bar{p}_2 = \frac{\langle x, x^{4/3} \rangle}{\langle x, x \rangle} = \frac{\int_{-1}^1 x^{7/3} dx}{\int_{-1}^1 x^2 dx} = 0 \cdot x$$

$$\bar{p}_3 = \frac{\langle 3x^2-1, x^{4/3} \rangle}{\langle 3x^2-1, 3x^2-1 \rangle} = \frac{\int_{-1}^1 3x^{10/3} - x^{4/3} dx}{\int_{-1}^1 9x^4 - 6x^2 + 1 dx} = \frac{48/91}{8/5} (3x^2-1)$$

$$\Rightarrow x^{4/3} \sim \bar{p} = \frac{3}{7} \cdot 1 + \frac{48/91}{8/5} (3x^2-1)$$

$$(7.) \bar{y}_1 = \begin{pmatrix} -1 \\ -3 \\ 0 \\ -2 \end{pmatrix} \Rightarrow \bar{z}_1 = \frac{\bar{y}_1}{\|\bar{y}_1\|} = \begin{pmatrix} -0.2673 \\ -0.8018 \\ 0 \\ -0.5345 \end{pmatrix}$$

$$\bar{y}_2 = \bar{x}_2 + \frac{\langle \bar{x}_2, \bar{y}_1 \rangle}{\langle \bar{y}_1, \bar{y}_1 \rangle} \bar{y}_1 = \begin{pmatrix} -7.5 \\ -1.5 \\ 2 \\ 6 \end{pmatrix} \Rightarrow \bar{z}_2 = \frac{\bar{y}_2}{\|\bar{y}_2\|} = \begin{pmatrix} -0.7557 \\ -0.1511 \\ 0.2015 \\ 0.6046 \end{pmatrix}$$

$$\bar{y}_3 = \bar{x}_3 - \frac{\langle \bar{x}_3, \bar{y}_1 \rangle}{\langle \bar{y}_1, \bar{y}_1 \rangle} \bar{y}_1 - \frac{\langle \bar{x}_3, \bar{y}_2 \rangle}{\langle \bar{y}_2, \bar{y}_2 \rangle} \bar{y}_2 = \begin{pmatrix} -0.2415 \\ 0.3517 \\ 0.5787 \\ -0.4068 \end{pmatrix} \Rightarrow \bar{z}_3 = \frac{\bar{y}_3}{\|\bar{y}_3\|} = \begin{pmatrix} -0.2923 \\ 0.4258 \\ 0.7005 \\ -0.4925 \end{pmatrix}$$

$$\bar{y}_4 = \bar{x}_4 - \frac{\langle \bar{x}_4, \bar{y}_1 \rangle}{\langle \bar{y}_1, \bar{y}_1 \rangle} \bar{y}_1 - \frac{\langle \bar{x}_4, \bar{y}_2 \rangle}{\langle \bar{y}_2, \bar{y}_2 \rangle} \bar{y}_2 - \frac{\langle \bar{x}_4, \bar{y}_3 \rangle}{\langle \bar{y}_3, \bar{y}_3 \rangle} \bar{y}_3 = \begin{pmatrix} 1.2922 \\ -0.9692 \\ 1.6961 \\ 0.8077 \end{pmatrix} \Rightarrow \bar{z}_4 = \frac{\bar{y}_4}{\|\bar{y}_4\|} = \begin{pmatrix} 0.5216 \\ -0.3912 \\ 0.6846 \\ 0.3260 \end{pmatrix}$$

$$(8.) \bar{x}_1 = 1 \quad \bar{x}_2 = x \quad \bar{x}_3 = x^2$$

$$\bar{y}_1 = \bar{x}_1 \Rightarrow \bar{z}_1 = \frac{\bar{y}_1}{\|\bar{y}_1\|} = \frac{1}{\sqrt{\int_0^1 1 dx}} = \boxed{1}$$

$$\bar{y}_2 = \bar{x}_2 - \frac{\langle \bar{x}_2, \bar{y}_1 \rangle}{\langle \bar{y}_1, \bar{y}_1 \rangle} \cdot 1 = x - \frac{\int_0^1 x dx}{1} = x - \frac{1}{2} = x - \frac{1}{2}$$

$$\Rightarrow \bar{z}_2 = \frac{\bar{y}_2}{\|\bar{y}_2\|} = \frac{x - 1/2}{\sqrt{\int_0^1 (x - 1/2)^2 dx}} = \frac{x - 1/2}{\sqrt{1/12}} = \boxed{\sqrt{12} (x - 1/2)}$$

$$\bar{y}_3 = \bar{x}_3 - \frac{\langle \bar{x}_3, \bar{y}_1 \rangle}{\langle \bar{y}_1, \bar{y}_1 \rangle} \cdot 1 - \frac{\langle \bar{x}_3, \bar{y}_2 \rangle}{\langle \bar{y}_2, \bar{y}_2 \rangle} (x - 1/2) = x^2 - \frac{\int_0^1 x^2 dx}{1} - \frac{\int_0^1 x^3 - 1/2 x^2 dx}{\int_0^1 (x - 1/2)^2 dx} (x - 1/2)$$

$$= x^2 - \frac{1}{3} - \frac{1/12}{1/12} (x - 1/2)$$

$$= x^2 - (x - 1/2) - 1/3 = x^2 - x + 1/6$$

$$\Rightarrow \bar{z}_3 = \frac{\int_0^1 x^2 - x + 1/6}{\sqrt{\int_0^1 (x^2 - x + 1/6)^2 dx}} = \frac{x^2 - x + 1/6}{\sqrt{1/180}} = \boxed{\sqrt{180} (x^2 - x + 1/6)}$$

$$\Rightarrow \boxed{\bar{z}_1 = 1}$$

$$\boxed{\bar{z}_2 = \sqrt{12} (x - 1/2)}$$

$$\boxed{\bar{z}_3 = \sqrt{180} (x^2 - x + 1/6)}$$