Quasi-solution approach to Nonlinear Problems

Saleh Tanveer (Ohio State University)

Collaborators: O. Costin, M. Huang

Basic Idea

- Nonlinear problems, written as $\mathcal{N}[u] = 0$, are difficult to analyze unless nonlinearity is "weak" or has special structure
- However, if we find some u_0 with $\mathcal{N}[u_0] = R$ small and Initial/Boundary Conditions approximately satisfied, then $E = u - u_0$ satisfies

$$LE = -R - \mathcal{N}_1[E] ,$$

where $L = \mathcal{N}_u$ and $\mathcal{N}_1[E] = \mathcal{N}[u_0 + E] - \mathcal{N}[u_0] - \mathcal{L}E$

If *L* has suitable inversion for given small intial/boundary conditions and nonlinearity \mathcal{N}_1 is regular, then a contraction mapping argument can often be employed in a suitable space to analyze the weakly nonlinear problem:

$$E=-\mathcal{L}^{-1}R-\mathcal{L}^{-1}\mathcal{N}_1[E]$$

Remarks

This kind of inversion regularly employed in other contexts–for instance in determining error bounds for $|u - u_0|$ in perturbation problems of the type: $\mathcal{N}[u;\epsilon] = 0$ when $\mathcal{N}[u_0;0] = 0$

What does not seem to be recognized until recently is how to determine quasi-solution u_0 in a general, efficient and systematic manner.

Recently, there has been some work (Costin, Huang, Schlag, 2012), (Costin, Huang, T., 2012), (Costin, T., 2013), (T. 2013) in a number of different nonlinear ODE and integro-differential equation contexts. I will describe how computation typically based on orthogonal polynomials and exponential asymptotics (when domain extends to ∞) may be used to construct u_0 and bounds on E obtained.

Some Applications of quasi-solution approach

1. Dubrovin conjecture for P-1, $y'' = 6y^2 + z$: For the unique solution of P-1 satisying $y(z) = i\sqrt{\frac{z}{6}} (1 + o(1))$ as $e^{-i\pi/5}z \to +\infty$, the sector $\arg z \in (-\frac{3}{5}\pi, \pi)$ is singularity free. Problem arises in characterizing small dispersion effects on gradient blow-up for focussing NLS (Dubrovin, Grava, Klein, 2008)

2. Find solution *f* to Blasius similarity equation in $(0, \infty)$:

$$f'''+ff''=0\ ,\ \ f(0)=0=f'(0),\ \ \ \lim_{x o\infty}f'(x)=1$$

3. Existence of 2-D water waves of permanent form (Involves a nonlinear integro-differential equation)

Note: Nonconstructive proofs exist in cases 2. and 3.; not in 1

Blasius similarity problem

Blasius (1908) derived the two point BVP ODE:

 $f''' + ff'' = 0 ext{ in } (0,\infty) ext{ with } f(0) = 0 = f'(0) \ , \ \lim_{x o \infty} f'(x) = 1$

as similarity solution to fluid Boundary layer equations. Generalization include $f(0) = \alpha$, $f'(0) = \gamma$ Much work (Topfer, 1912, Weyl, '42, Callegari & Friedman '68, Hussaini & Lakin '86, others. Existence and uniqueness known. Related problem:

F''' + FF'' = 0 in $(0, \infty)$ with F(0) = 0 = F'(0), F''(0) = 1

If $\lim_{x
ightarrow\infty}F'(x)=a>0$, then $f(x)=a^{-1/2}F\left(a^{-1/2}x
ight)$.

Though this transformation, the two point BVP is turned into an initial value problem; though convenient, transformation not needed for quasi-solution approach.

Definitions

Let

$$P(y) = \sum_{j=0}^{12} \frac{2}{5(j+2)(j+3)(j+4)} p_j y^j \tag{1}$$

where $\left[p_{0},...,p_{12}
ight]$ are given by

\int 510	18523	42998	113448	65173 3	890101	2326169
$\lfloor -104451 \rfloor$	49', -5934'	$-\frac{1}{441819}$	81151,	-22093, -2000,	6016, -	9858,
4134879	1928001 2	0880183	1572554	1546782	13152	ן41
$\boxed{7249}, -$	-1960, $-$	19117, -	$\frac{1}{2161},$	5833	3223	9
						(2)

Define

$$t(x) = \frac{a}{2}(x+b/a)^2, \ I_0(t) = 1 - \sqrt{\pi t}e^t \operatorname{erfc}(\sqrt{t}),$$
$$J_0(t) = 1 - \sqrt{2\pi t}e^{2t}\operatorname{erfc}(\sqrt{2t}) \quad (3)$$

Main Results

$$q_0(t) = 2c\sqrt{t}e^{-t}I_0 + c^2 e^{-2t} \left(2J_0 - I_0 - I_0^2\right), \qquad (4)$$

Theorem: Let F_0 be defined by

$$F_{0}(x) = \begin{cases} \frac{x^{2}}{2} + x^{4} P\left(\frac{2}{5}x\right) & \text{for } x \in [0, \frac{5}{2}] \\ ax + b + \sqrt{\frac{a}{2t(x)}} q_{0}(t(x)) & \text{for } x > \frac{5}{2} \end{cases}$$
(5)

Then, there is a unique triple (a, b, c) close to $(a_0, b_0, c_0) = \left(\frac{3221}{1946}, -\frac{2763}{1765}, \frac{377}{1613}\right)$ in the sense that $(a, b, c) \in S$ where

$$S = \left\{ (a, b, c) \in \mathbb{R}^3 : \sqrt{(a - a_0)^2 + \frac{1}{4}(b - b_0)^2 + \frac{1}{4}(c - c_0)^2} \\ \le \rho_0 := 5 \times 10^{-5} \right\}$$
(6)

with the property that F_0 is an approximation to true solution F to the IVP.

Main Results

More precisely,

$$F(x) = F_0(x) + E(x)$$
, (7)

where the error term $oldsymbol{E}$ satisfies

$$\|E''\|_{\infty} \le 3.5 \times 10^{-6}, \|E'\|_{\infty} \le 4.5 \times 10^{-6}, \|E\|_{\infty} \le 4 \times 10^{-6} \text{ on } [0, \frac{5}{2}]$$
(8)

and for $x \geq rac{5}{2}$

$$\begin{split} \left| E \right| &\leq 1.69 \times 10^{-5} t^{-2} e^{-3t} , \left| \frac{d}{dx} E \right| \leq 9.20 \times 10^{-5} t^{-3/2} e^{-3t} \\ &\left| \frac{d^2}{dx^2} E \right| \leq 5.02 \times 10^{-4} t^{-1} e^{-3t} \end{split}$$
(9)

Construction of quasi-solution F_0 for Blasius

- Use numerical calculations and projection to Chebyshev basis on $\mathcal{I} = \left[0, \frac{5}{2}\right]$.
- The residual $R = F_0''' + F_0 F_0''$ is a polynomial of degree 30; we project it to Chebyshev basis: $R(x) = \sum_{j=0}^{30} r_j T_j \left(\frac{4}{5}x - 1\right)$ and estimate $||R||_{\infty} \leq \sum_{j=0}^{30} |r_j| \leq 5 \times 10^{-7}$. Procedure generalizable to multi-variables using product space representation. For interval $I = \left[\frac{5}{2}, \infty\right)$, any solution for which $F'(x) \to a > 0$ as
- $x \to \infty$ has the representation F(x) = ax + b + G(x) where G is exponentially small.
- Applying exponential asymptotics theory (Costin, '98),

$$G(x) = \sqrt{rac{a}{2t(x)}}q(t(x))$$
, where $q(t) = \sum_{n=1}^{\infty} \xi^n Q_n(t)$, where $\xi = rac{ce^{-t}}{\sqrt{t}}$

Two term trucation provides quasi-solution with small residual.

Analysis of Error term

- To complete quasi-solution, need (a, b, c) approximately-through numerical matching.
- Note: Quasi solution determined empirically; not unique. Anything that gives small residual *R* and approximately satisfies boundary/initial condition is a candidate.
- Rigor needed in proving R is uniformly small and that $E = F F_0$ satisfying

$$LE := E'' + F_0 E'' + EF_0'' = -R - EE'',$$

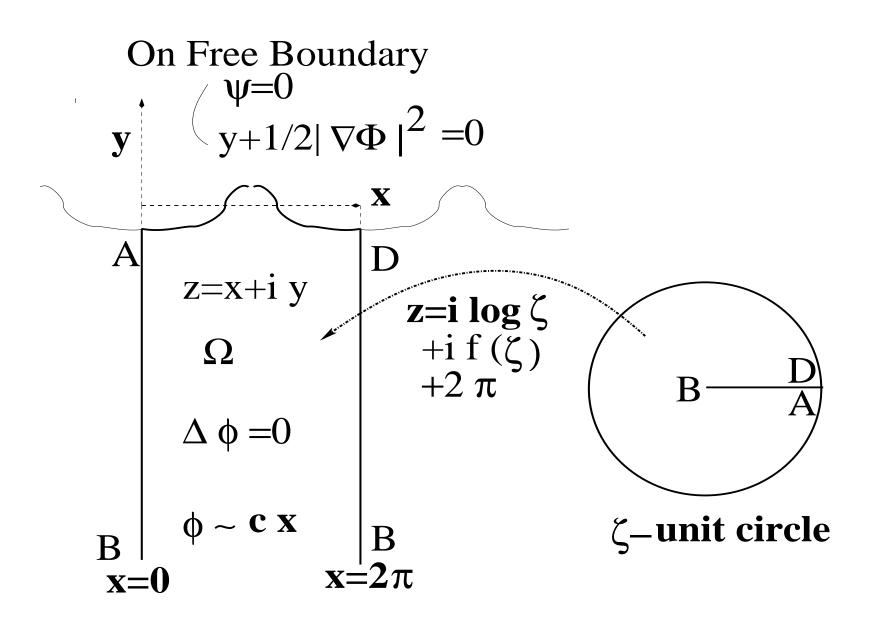
and small initial/boundary conditons has a small bound.

The analysis for *E* involves inversion of *L* subject to initial/boundary conditions and use of contraction arguments in appropriate spaces. It is detailed and matching arguments at $\frac{5}{2}$ are delicate but not out of the ordinary. We skip details.

Quasi-solution approach for general systems

- The procedure described is quite general. For proving Dubrovin conjecture for P-1: $y'' = 6y^2 + z$, we used a similar argument in the complex *z*-plane.
- No a priori limitation on the size of the system or the number of variables/parameters, though the method is most transparent for one independent variable. Error bound checks become more computer assisted with multi-variables and parameters.
- Rigorous error control does not need explicit Green's function; energy methods will do as long as residual E is small.
- The accuracy can in principle be arbitrary, though the number of terms needed in the quasi-solution may become prohibitive for too high an accuracy. In some problems, inversion of L can give rise to large bounds; in some cases one may need make arguments in sub-domains to obtain refined estimates.

2-D symmetric steady water waves



Background

- Extensive history of water waves for more then 200 years, starting with Laplace, Langrange, Cauchy, Poisson, Airy, Stokes, ...
- Rigorous work for small amplitude waves by Nekrasov (1921), Levi-Civita (1924)
- Large Amplitude Wave analysis by Krasovskii (1961), Keady and Norbury (1978), Amick and Toland (1981)
- Numerical calculations also by a number of people including Longuet-Higgins and Cokelet, Schwartz in midseventies
- Other variations include waves with nonzero vorticity, finite depth fluid, limiting cases lead to the KdV (work by Strauss, Bona, \cdots

Conformal Mapping approach

Steady symmetric 2-D water waves is equivalent to determining analytic function f in $|\zeta| < 1$ with property $1 + \zeta f' \neq 0$ in $|\zeta| \leq 1$ and satisfying

$$\operatorname{Re} f = -rac{c^2}{2 \left|1+\zeta f'
ight|^2} \hspace{0.2cm} ext{on} \hspace{0.2cm} |\zeta| = 1$$

The wave height $h = \frac{1}{2} [f(-1) - f(+1)]$. One seeks (f, c) for given h. For efficiency in representation, better to use

$$f = \sum_{j=0}^\infty f_j \eta^j \ , \ ext{where} \ \eta = rac{\zeta+lpha}{1+lpha\zeta},$$

where $\alpha \in (0, 1)$ chosen in accordance to $\alpha = \frac{22}{27}h + \frac{3}{2}h^2 + 3h^3$ for $h \in (0, h_M)$, where $h_M \approx 0.4454 \cdots$ correspond to Stokes highest wave that makes 120^o angle at the apex.

Representation in the η domain

$$\operatorname{Re} f = -\frac{c^2}{2\left|1 + q(\eta)\eta f'(\eta)\right|^2} \text{on } |\eta| = 1 \text{ where}$$
$$q(\eta) = \frac{(\eta - \alpha)(1 - \alpha\eta)}{\eta(1 - \alpha^2)}$$

We define quasi-solution (f_0, c_0) so that f_0 is analytic in $|\eta| < 1$ and on $\eta = e^{i\nu}$, $R_0(\nu)$ and $R'_0(\nu)$ are small, where

$$R_0(
u) = \left| 1 + q(\eta) \eta f_0'(\eta)
ight|^2 {
m Re}\, f_0 + rac{c_0^2}{2}$$

Also, require

$$(1+\eta q f_0')
eq 0 ext{, for } |\eta|\leq 1$$

Note f_0 is a polynonomial of order n, $R_0(\nu)$ is a polynomial in $\cos \nu$ of order 2n + 1.

Change of dependent variables

$$w=-rac{2}{3}\log c+\log\left(1+\eta q f'
ight) ext{, implying} \left|1+\eta q f'
ight|=c^{2/3}e^{\operatorname{Re}w} ext{,}$$

then w satisfies

$$\frac{d}{d\nu}\operatorname{Re} w + q^{-1}e^{2\operatorname{Re} w}\operatorname{Im} e^w = 0 \text{ for } \eta = e^{i\nu}$$

We note

$$w(\eta) = \sum_{j=0}^{\infty} b_j \eta^j$$
, where b_j is real

Since $q(\alpha) = 0$, it follows that $w(\alpha) = -\frac{2}{3}\log c$, i.e

$$-rac{2}{3}\log c = \sum_{j=0}^{\infty} b_j lpha^j$$

Quasi-solution under change of variable

Corresponding to the quasi-solution f_0 , we define

$$w_0=-rac{2}{3}\log c_0+\logig(1+\eta q(\eta)f_0'ig)$$

Then, we can check that w_0 satisfies

$$\frac{d}{d\nu}\operatorname{Re} w_0 + q^{-1}e^{2\operatorname{Re} w_0}\operatorname{Im} e^{w_0} = R(\nu) := -\frac{R_0'(\nu)}{c_0^2 - 2R_0} - \frac{4A(\nu)R_0(\nu)}{3(c_0^2 - 2R_0)},$$

$$2A(
u) = 3q^{-1}e^{2\operatorname{Re}w_0}\operatorname{Im}\left\{e^{w_0}
ight\} = rac{3}{c_0^2}\operatorname{Im}(\eta f_0') \Big| 1 + \eta q f_0' \Big|^2,$$

$$h_0 = -rac{(1-lpha^2)}{2} \int_{-1}^1 rac{e^{w_0(\eta) - w_0(lpha)} - 1}{(\eta - lpha)(1-lpha\eta)} d\eta ext{, with } h - h_0 ext{ small}$$

Weakly nonlinear formulation for $W = w - w_0$

 $W = w - w_0 := \Phi + i \Psi$ on $\eta = e^{i
u}$ satisfies:

$$\mathcal{L}\left[\Phi
ight]:=rac{d}{d
u}\Phi+2A(
u)\Phi+2B(
u)\Psi= ilde{\mathcal{M}}[W]-R(
u)=:r(
u) \ ,$$

$$2B(
u) = q^{-1}e^{2\operatorname{Re}w_0}\operatorname{Re}\left\{e^{w_0}
ight\} = rac{1}{c_0^2}\left[1+q\eta f_0'
ight]\left|1+\eta q f_0'
ight|^2,$$

$$ilde{M}[W] := -rac{2}{3} A(
u) M_1 - 2 B(
u) M_2 \ ,$$

where $M_1 = e^{2\operatorname{Re}\ W}$ Re $e^W - 1 - 3\operatorname{Re}\ W$, $M_2 = e^{2\operatorname{Re}\ W}$ Im $e^W - \operatorname{Im} W$

Note

$$\Psi(
u) = rac{1}{2\pi} PV \int_0^{2\pi} \Phi(
u') \cot rac{
u -
u'}{2} d
u'$$

Need inversion of ${\cal L}$ to obtain a weakly nonlinear integral equation for Φ

Water wave error: Function Spaces

Definition: For fixed $\beta \geq 0$, define \mathcal{A} to be the space of analytic functions in $|\eta| < e^{\beta}$ with real Taylor series coefficient at the origin, equipped with norm:

$$\|W\|_{\mathcal{A}} = \sum_{l=0}^{\infty} e^{eta l} \Big| W_l \Big| \,\,,\,\, ext{where}\,\, W(\eta) = \sum_{l=0}^{\infty} W_l \eta^l$$

Define \mathcal{E} to be the Banach space of real 2π -periodic even functions ϕ so that

$$\phi(
u) = \sum_{j=0}^{\infty} a_j \cos(j
u) ext{, with norm } \|\phi\|_{\mathcal{E}} := \sum_{j=0}^{\infty} e^{eta j} |a_j|$$

Define S to be Banach space of real 2π - periodic odd functions

$$\psi(
u) = \sum_{j=1}^\infty b_j \sin(j
u) ext{, with norm } \|\psi\|_{\mathcal{S}} := \sum_{j=1}^\infty e^{eta j} |b_j| < \infty$$

Control on error $W = w - w_0$

Define \mathcal{E}_1 subspace of \mathcal{E} so that for $\Phi \in \mathcal{E}_1$,

$$\Phi = a_0 + \sum_{j=2}^{\infty} a_j \cos(j
u)$$

When certain conditions depending on quasi-solution hold, then the most general solution of $\mathcal{L}\Phi = r$ is given by

 $\Phi = \mathcal{K}r + a_1G,$

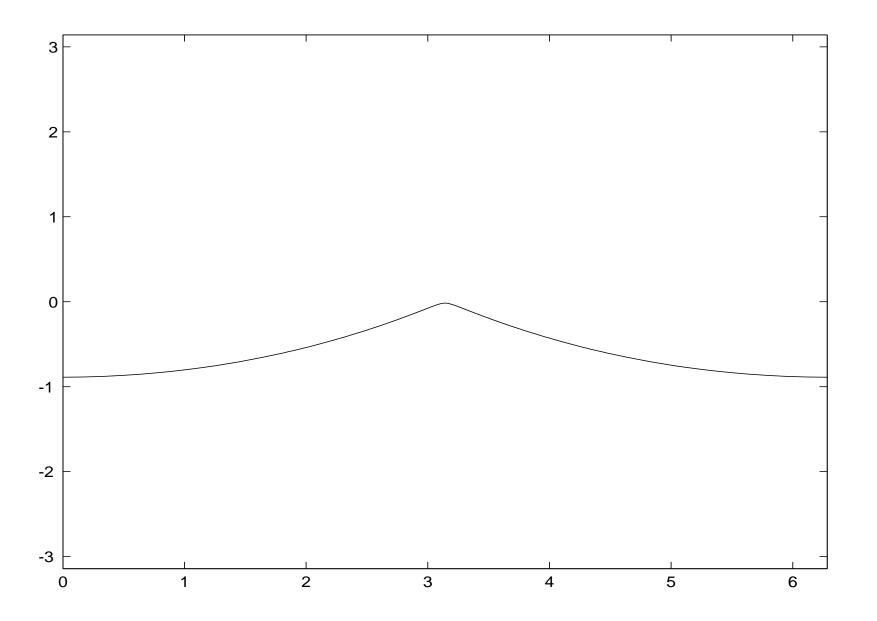
where $\mathcal{K}: \mathcal{S} \to \mathcal{E}_1$ is a bounded operator with norm M that may be estimated and $G \in \mathcal{E}$

Proving steady symmetric water waves equivalent to proving solution to weakly nonlinear integral equation:

 $\Phi = -\mathcal{K}[R] - \mathcal{K}\mathcal{M}[\Phi] + a_1G =: \mathcal{N}[\Phi],$

for each $a_1 \in (-\epsilon_0, \epsilon_0)$ small enough interval, height constraint determines a_1 . For a range of height $h \in (0, h_M)$, we show \mathcal{N} is contractive for chosen quasi-solutions (f_0, c_0)

Water Wave with h = 0.4359, highest speed



Accurate quasi-solution for h = 0.4359

In this case $c_0 = \frac{254979}{233294}$, $\alpha = \frac{7997989622533}{900000000000}$. Quasi-solution:

$$\tilde{f}_0 = b_0 + \sum_{j=1}^{15} \frac{b_j}{j} \eta^j + \sum_{m=1}^{6} \lambda_m \gamma_m^{-1} \log (1 + \gamma_m \eta)$$
, where

 $\mathbf{b} = \left[-\frac{7491}{33875}, \frac{3496}{95411}, \frac{421}{16231}, \frac{991}{116428}, \frac{6053}{1113170}, \frac{939}{445538}, \frac{2921}{2444353}, \frac{325}{2444353}, \frac{359}{1442979}, \frac{229}{2029023}, \frac{213}{4708117}, \frac{111}{5158825}, \frac{31}{4858465}, \frac{24}{7621883}, \frac{34}{64439691}, \frac{33}{123015796} \right]$

$$\gamma = \left[\frac{30266}{33767}, -\frac{39823}{44724}, -\frac{36643}{43855}, \frac{9341}{11348}, -\frac{46141}{64708}, \frac{17251}{25880}\right]$$
$$\lambda = \left[-\frac{6067}{596979}, -\frac{42304}{88055}, \frac{1889}{11944}, -\frac{509}{48108}, \frac{5220}{59461}, -\frac{2169}{181300}\right]$$

Quasi-solution as function of *h*

- Quasi-solution representation available as a function of height h as well. For smaller heights $h \leq \frac{3}{10}$ uniform expression involving polynomial of 15 th order in η and 5-th order in h.
- For larger heights, better to use representation for small intervals in h in terms of low order polynomials in h
- Rigorous error control possible for smaller heights uniformly in h; but for larger heights, the proof with h parameter becomes unwieldly. We can give good bounds for the worst case; *i.e.* largest height we tried, h = 0.4359.

Conclusion

- 1. With suitable quasi-solution u_0 , many strongly nonlinear problems can be analyzed through weakly nonlinear analysis.
- 2. No *a priori* bar on the number of variables and/or parameters, as long as suitable bounds on inversion of Frechet derivative is possible; analysis most transparent for problems in one variable with no parameters. Otherwise, the error estimate calculation is more computer assisted.
- 3. ODE or systems of ODEs, including two point boundary value problems are easily amenable. Opens the opportunity for homoclinic-heteroclinic determination in higher dimension.
- 4. PDE similarity blow up or spectral analysis in 1+1 dimension amenable to our type of analysis.
- 5. Look forward to working with colleagues here.
- 6. Papers available online.

Linear Problem $\mathcal{L}\Phi = r$ for given a_1 and r

We seek solution $\Phi = \sum_{j=0}^{\infty} a_j \cos(j\nu) \in \mathcal{E}$ to $\mathcal{L}\Phi = r$ for given $a_1 \in (-\epsilon_0, \epsilon_0)$ and $r = \sum_{j=1}^{\infty} r_j \sin(j\nu)$. Equivalent to solving for $a = (a_0, 0, a_2, a_3, \cdots) \in H$ for given a_1 and $r = (0, r_1, r_2, r_3, \cdots) \in H$, where H is the weighted l^1 space with norm $||g||_H = \sum_{j=0}^{\infty} e^{\beta l} |g_l|$ and the following equations are satisfied:

$$a_0 + \sum_{l=2}^{\infty} \frac{a_l}{2A_1} \left(A_{l+1} - A_{l-1} + B_{l-1} - B_{l+1} \right) = \frac{r_1}{2A_1} + \frac{1}{2A_1} \left(1 - 2B_0 - A_2 \right)$$

$$\frac{2A_k}{l_k}a_0 + \sum_{l=2}^{k-1} \frac{a_l}{l_k} \left(A_{k-l} + A_{l+k} + B_{k-l} - B_{l+k}\right) - a_k$$

 $+\sum_{l=k+1}^{\infty} \frac{a_l}{l_k} \left(A_{l+k} - A_{l-k} + B_{l-k} - B_{l+k} \right) = \frac{r_k}{l_k} - \frac{a_1}{l_k} \left(A_{k-1} + A_{k+1} + B_{k-1} \right)$